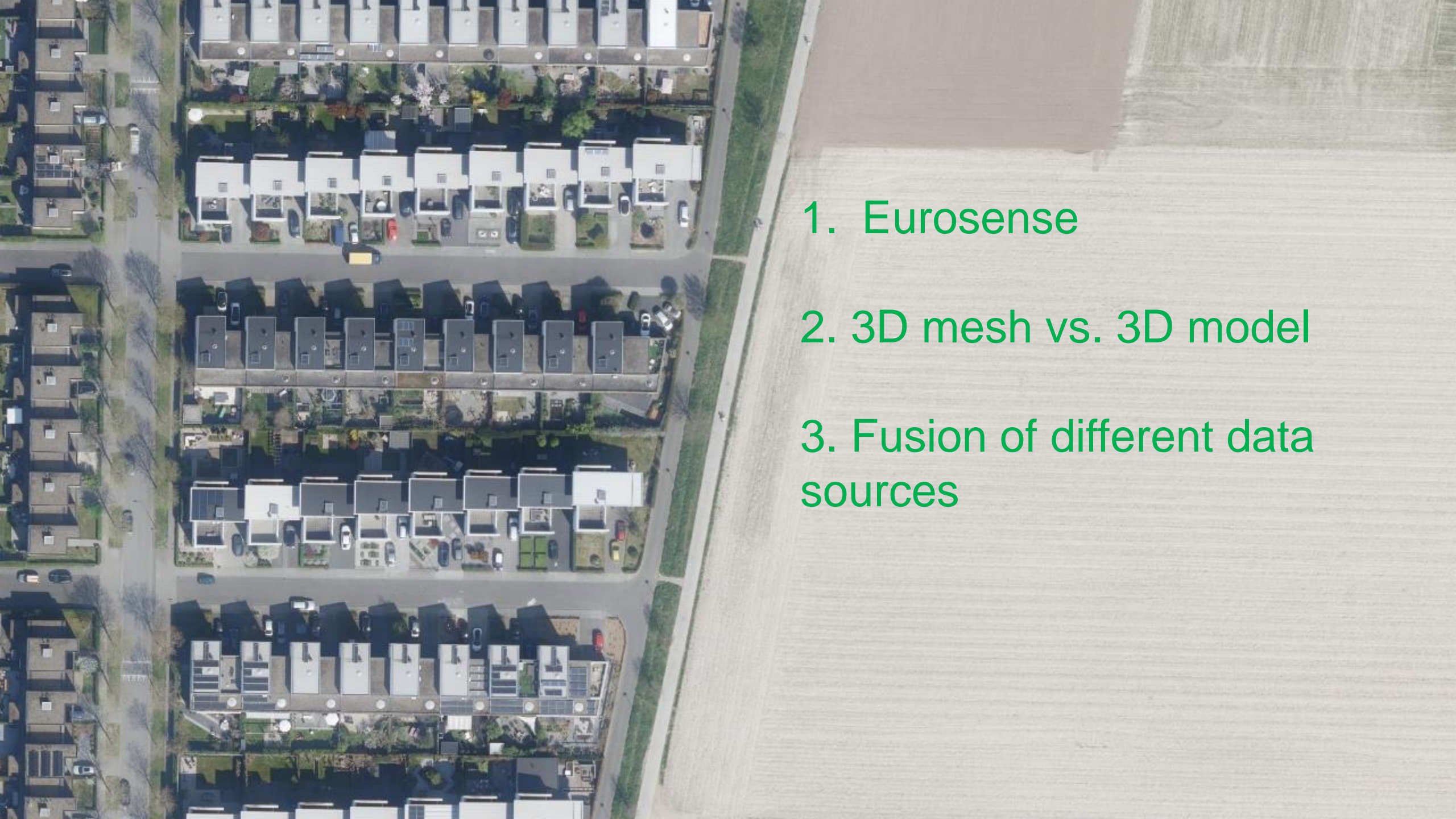




BeGeo 2020

**The ultimate 3D model:
A combination of different data sources**

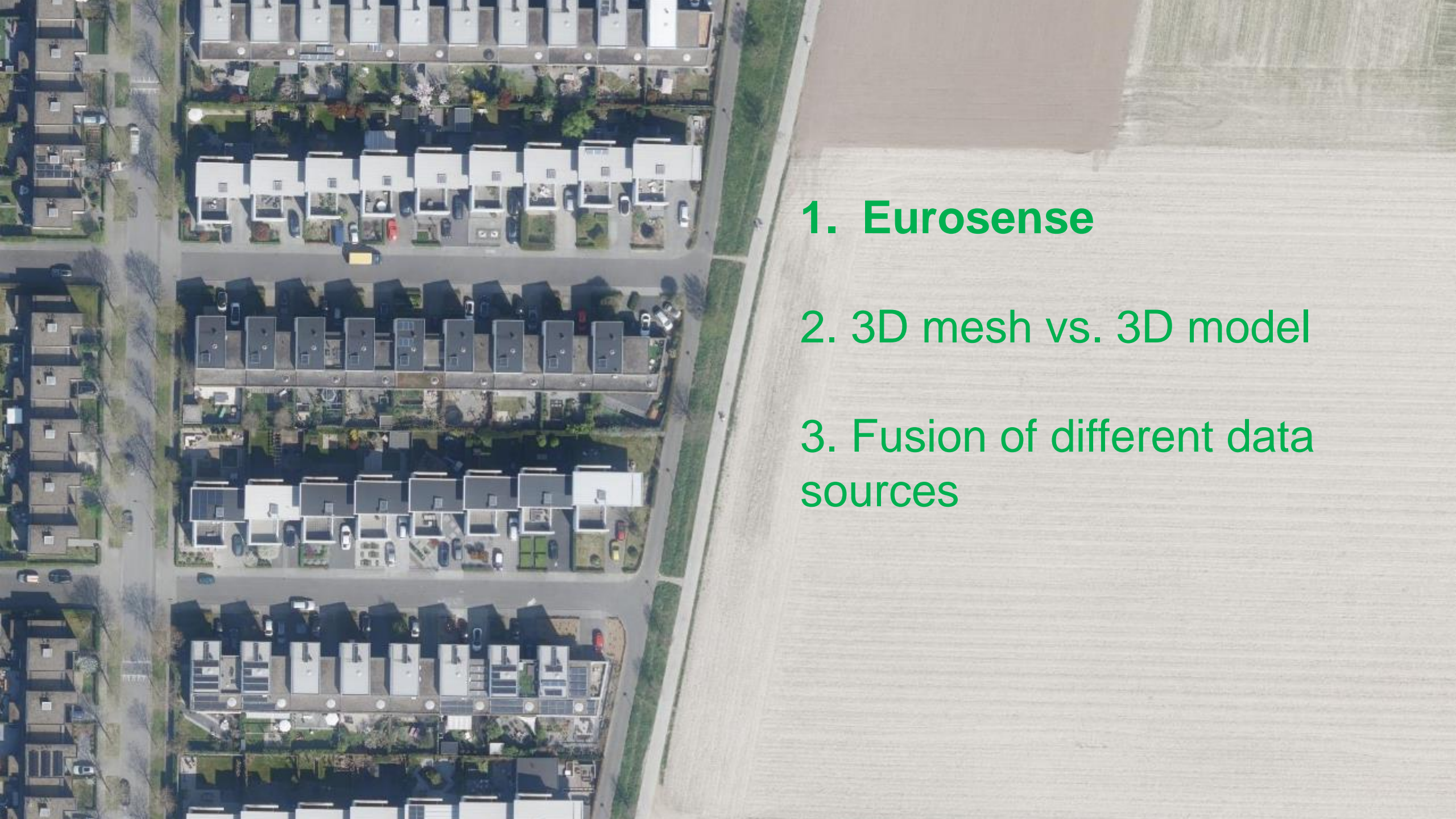
Victoria Jadot
October 27, 2020



1. Eurosense

2. 3D mesh vs. 3D model

3. Fusion of different data
sources



1. Eurosense

2. 3D mesh vs. 3D model

3. Fusion of different data sources

Introduction



>130
colleagues in
10 Eurosense
offices across
Europe

Integration of
airborne and
spaceborne
data

56 years of
experience

**International
cooperation:** founding
member of **EAASI**
(European Association
of Aerial Surveying
Industries) & **EARSC**
(European Association
of Remote Sensing
Companies)

EAASI
FOUNDING
MEMBER



Strong
collaboration
with Esri

EARSC
European Association
of Remote Sensing
Companies
FOUNDING
MEMBER



Equipment



Vexcel Eagle Mark 3
large format camera
(footprint of 450
Megapixels and
resolution down to
2cm)

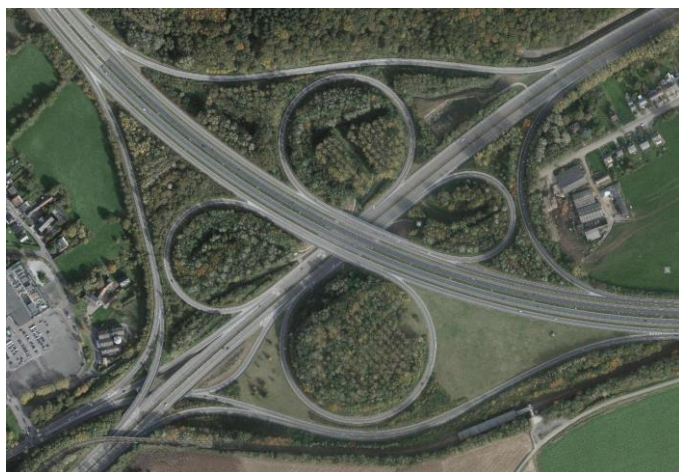


Riegl VQ 1560 II
(pulse frequency of 4
GHz) with integrated
Phase One medium-
format 150 Mpx
camera

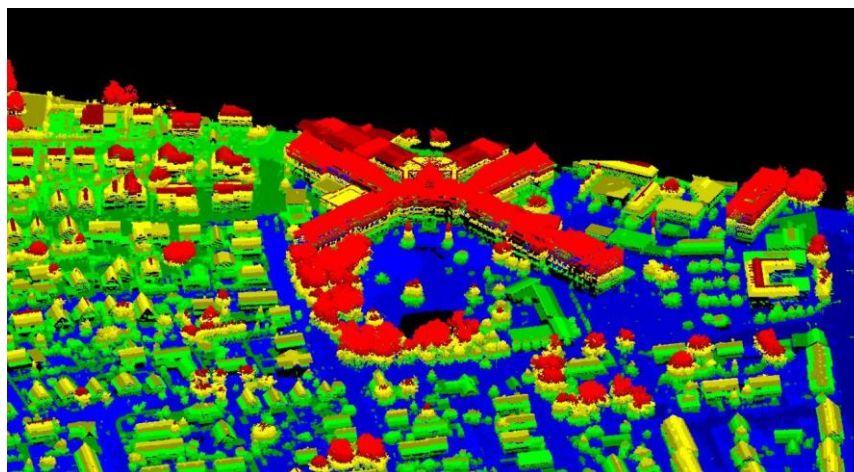


Thermographic cameras
(Flir)

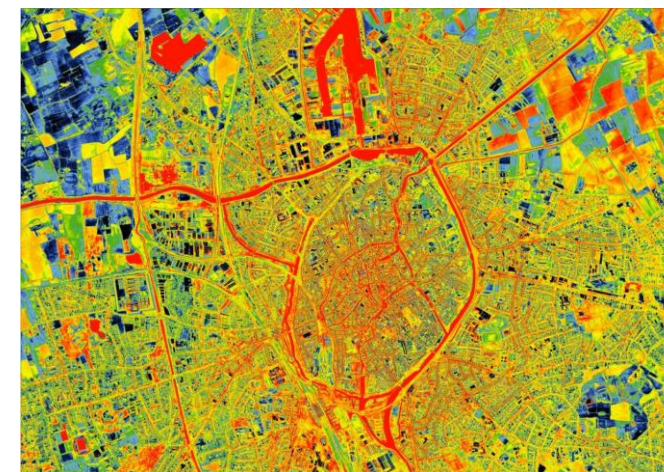
Equipment and products



(True) orthophotos



LiDAR measurements



Thermal maps

And also...



Change
detection

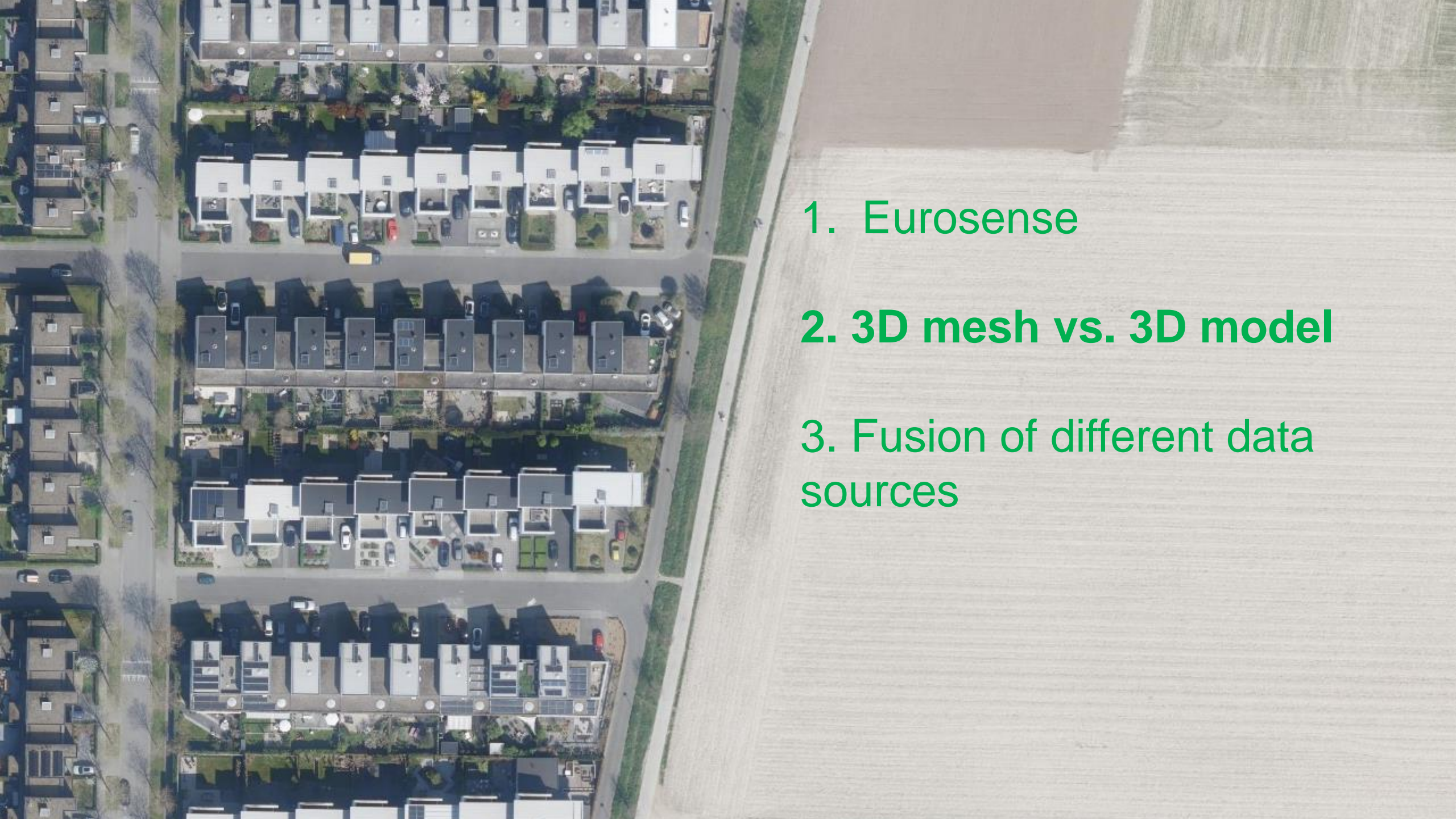
Tree inventory
and health
analysis

...

GRB
enrichment
and update

Obstacle
mapping
(airports)

Land cover
classification



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3D mesh



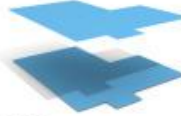
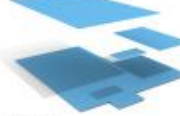
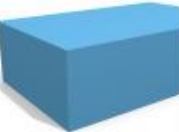
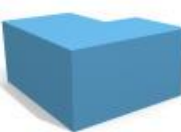

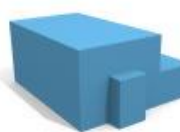










All videos
are available
on
Eurosense's
YouTube
channel

3D model



3D model

	LOD x.0	LOD x.1	LOD x.2	LOD x.3
LOD0	 LOD0.0	 LOD0.1	 LOD0.2	 LOD0.3
LOD1	 LOD1.0	 LOD1.1	 LOD1.2	 LOD1.3
LOD2	 LOD2.0	 LOD2.1	 LOD2.2	 LOD2.3
LOD3	 LOD3.0	 LOD3.1	 LOD3.2	 LOD3.3

LOD 2.2. –
LOD 3.0 ?



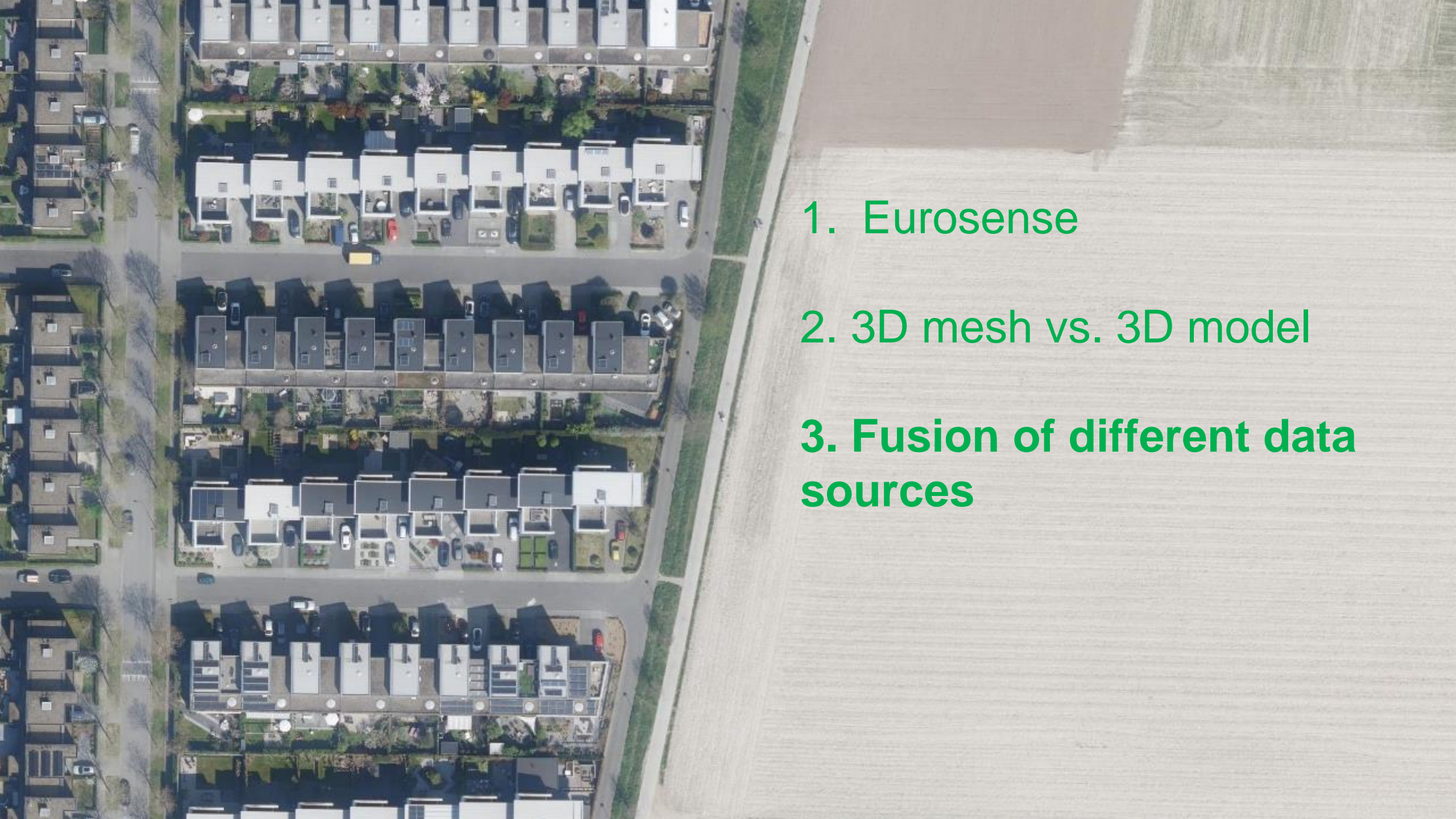
Textured
LOD 2.3.



3D model



- Plug in BIM-model into 3D-model
- Link with (digital) legal and administrative framework to evaluate automatically and rapidly the necessary permits → immediately straightforward report to see if project is compliant or not



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sources

Possible data sources



Aircraft

Mobile mapping



Backpack system



Objective: to complete 3D models with data at street level and inside

Challenges



- “Stitch” data together (vectorized 3D-model and texture overlay)
- Different accuracies of source data (airborne LiDAR, photogrammetry, mobile LiDAR, mobile images, backpack system,...)
- LiDAR: automatic vectorisation
- Different software and different data formats

Progress



- Airborne + mobile mapping
- LiDAR and imagery



Progress



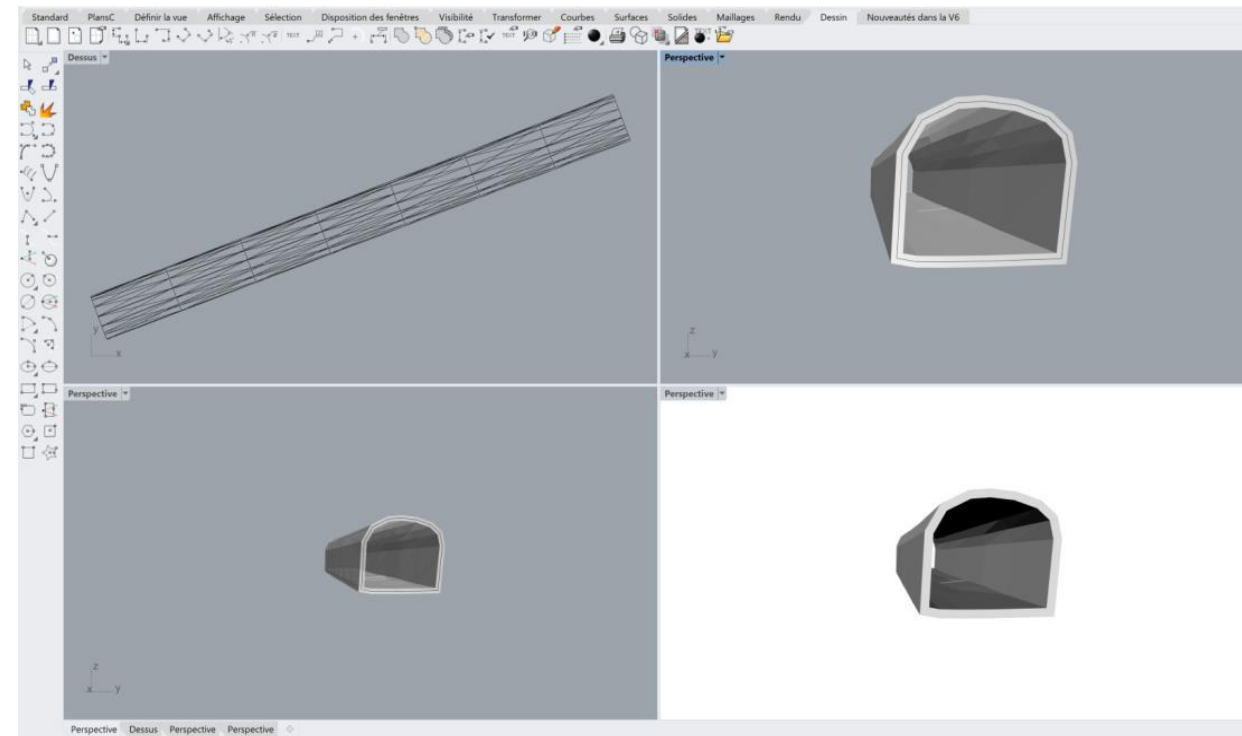
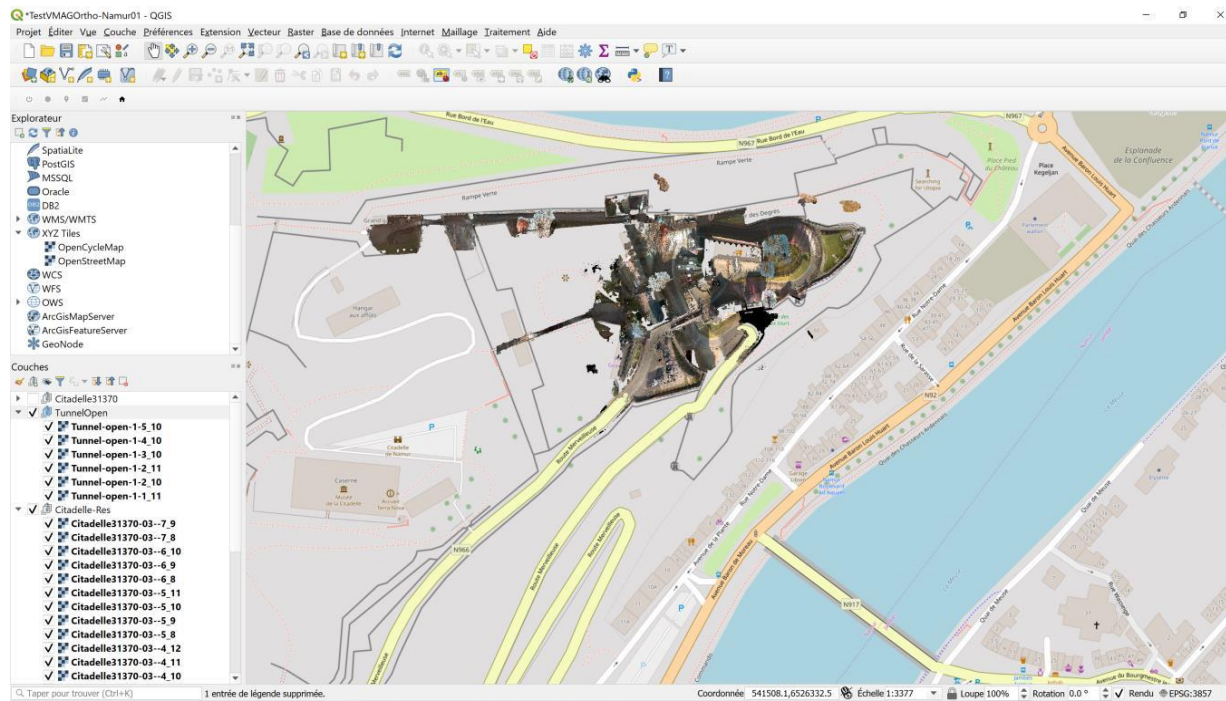
- Indoor mapping
- LiDAR and imagery



Progress



- Indoor mapping
- LiDAR and imagery



The future...



- Seamless fusion of different data sources
- Towards LOD 3.3
- Integration with external data bases and real time data (IoT)
- 5D: XYZ, time, cost



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02/460.70.00